

# Nicholas Mattos

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## EDUCATION

- Georgia Institute of Technology – Atlanta, GA** Expected Graduation: May 2030  
*Doctor of Philosophy in Mechanical Engineering* | Robotics and Control | Physical AI | Mechanics
- Stevens Institute of Technology – Hoboken, NJ** Graduation: May 2026  
*Master of Engineering in Mechanical Engineering* | Concentration in Robotics and Control  
*Graduate Certificate in Robotics and Control* | *Graduate Certificate in Medical Devices* | GPA: 4.0
- Seton Hall University – South Orange, NJ** Graduation: Dec 2024  
*Bachelor of Science in Physics* | GPA: 3.87

## EMPLOYMENT

- Georgia Institute of Technology, Graduate Research Assistant** – Atlanta, GA Aug 2026 – Present  
*Advisor: Professor Shuman Xia | Co-Advisor: Professor Yue Chen*
- Develop a physical AI robotic cutting platform for soft-material interaction, integrating robot control, vision systems, sensing, and experimental validation.
  - Validate system on an in-house da Vinci surgical robotic system for autonomous soft-tumor phantom manipulation.
- EN-POWER GROUP, Mechanical Design Engineering Intern** – New York, NY May 2024 – Present  
*Mechanical and energy engineering consulting firm serving commercial and residential buildings*
- Conduct building area measurements for 100+ contracts totaling \$500,000+ using AutoCAD, supporting energy efficiency compliance for NYC LL97/LL84 benchmarks.
  - Collaborate on HVAC system design, load calculations, equipment sizing, and NYC DOB submittal review.
- MICRO, Automation/Process Development Engineering Co-op** – Somerset, NJ Jan 2026 – May 2026  
*Contract medical device manufacturer producing components, assemblies, and robotic systems in regulated environments*
- Designed and implemented robotic automation solutions, including FANUC programming (TP/KAREL), sensor integration, PLC-based control logic, and EOAT/fixtures design.
  - Developed and integrated PLC-based control systems using Allen-Bradley Studio 5000 Logix Designer and AutomationDirect platforms, enabling robot-PLC communication, I/O mapping, coordinated control, conditional actuation, HMI design for operator interaction, and MES integration across work centers.
  - Led development of an AWS Quick Suite, an integrated AI tool for natural language querying of manufacturing data, while supporting process development and validation (IQ/OQ) in an FDA/ISO regulated GMP environment.
  - Assisted in FAT/SAT for semi-automated crimping cell for high precision cryogenic surgical tools.
- Stevens Institute of Technology, Graduate Research Assistant** – Hoboken, NJ Sep 2025 – May 2026  
*Advisor: Professor Long Wang | Funded by the Department of Defense (DoD)*
- Collaborate with Medtronic and Corvid Technologies and under contract with the Defense Health Agency.
  - Develop a robotic end effector for combat casualty care based on design inputs provided by the DoD.
  - Integrate hardware control, 3D-printed assemblies, and SolidWorks-based design to support prototype validation and future Food and Drug Administration (FDA) activities.
- Stevens Institute of Technology, Graduate Teacher Assistant** – Hoboken, NJ Jan 2025 – May 2026
- TA for Fluid Mechanics ME 342 (Spring 2025) and Engineering Analysis I ME 641 (Fall 2025 and Spring 2026).

## PROJECTS

- Autonomous Mobile Robot Sorting & Navigation**
- Engineered a state-based control and navigation system for a differential-drive robot, enabling autonomous identification, sorting, and relocation of colored objects in simulation.
- Kinematic Modeling & Simulation of a 5-DOF Robotic Manipulator**
- Developed forward and inverse kinematic algorithms to model robotic motion, validate workspace constraints, and optimize end-effector trajectory planning.
- Vision-Based Object Detection & Localization Pipeline for Autonomous Navigation Application**
- Engineered a computer vision pipeline for object detection and spatial localization, processing visual data to accurately identify and map obstacles for autonomous navigation systems.

## TECHNICAL SKILLS

**Software/Programming:** MATLAB, Simulink, Python, PLC Ladder Logic, HMI Design, Arduino, TP/KAREL (FANUC), ROS 2, C++  
**CAD/Design:** SolidWorks, AutoCAD, Creo, Fusion 360, FEA, 3D Printing, GD&T  
**Languages:** Spanish (Intermediate), Greek (Elementary)  
**Familiarities:** ISO 9001, ISO 14001, ISO 13485, 21 CFR Part 820, GMP Documentation Practices, Design Control, IQ/OQ Validation  
**Additional Skills:** Analysis (Minitab), Data Analysis (Excel), MES Integration  
**Awards:** Dean's List (all semesters), Eagle Scout, FRHSD Award (Perfect SAT Math Score), Sigma Pi Sigma (Physics and Astronomy Honor Society)